Scaling dictates the decoder structure

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ABSTRACT

Despite variability in embryo size, the tissue, organ and body plan develop \textit{in proportion} with embryo size, known as the scaling phenomenon\textsuperscript{1-7}. Scale-invariant patterning of gene expression is a common feature in development and regeneration, and can be generated by mechanisms such as scaling morphogen gradients\textsuperscript{8,9} and dynamic oscillation\textsuperscript{10,11}. However, whether and how static non-scaling morphogens (input) can induce a scaling gene expression (output) across the entire embryo is not clear\textsuperscript{2,12,13}. Here we show that scaling requirement sets severe constraints on the geometric structure of the input-output relation (the decoder), from which information about the regulation and mutants’ behavior can be deduced without going into any molecular details. We applied and tested our theory on \textit{Drosophila} gap gene system\textsuperscript{14-17} using the three maternal gradients (Bcd, Nos and Tor) as input. Remarkably, the parameter-free decoder correctly and quantitatively accounted for the gap gene expression patterns in nearly all morphogen mutants. It also revealed the regulation logic and the coding/decoding strategy of the gap gene system. Our work provides a general theoretical framework on a large class of problems where scaling output is induced by non-scaling input, as well as a unified understanding of scaling, mutants’ behavior and regulation in the \textit{Drosophila} gap gene and related systems.
In development and regeneration, a cell has to know its position in space in order to determine its fate. Often this positional information is encoded in a space-dependent signal like morphogen gradient\textsuperscript{2,14,18}. The decoder in the cell (usually gene networks) reads the local value of the signal to infer its spatial position by expressing the appropriate genes, as exemplified in the French-flag model\textsuperscript{2,19,20}. A common feature in these processes is that the gene expression pattern generated by the decoder is often scale-invariant with respect to fluctuations in the overall length of the system, which ensures the organism develops in the correct proportion\textsuperscript{6,7,21-24}. A scale invariant output can be achieved with a scale invariant input. Indeed, this strategy is adopted by systems such as Xenopus embryo\textsuperscript{8,25}, Drosophila wing\textsuperscript{9,26,27} and probably Drosophila dorsoventral axis\textsuperscript{28}, where the morphogen itself scales with the system size. However, achieving scale-invariant patterning from non-scaling morphogens is still largely an open question. A prototypical example is the scaling of Drosophila segmentation gene patterning\textsuperscript{12,23,29-35}, in which the gradients of the maternal morphogens seem to have fixed length constants that do not scale with the embryo size\textsuperscript{29,33,35-38}. In this paper, we first establish a general theoretical framework. We show that the necessary and sufficient condition for a decoder to generate a scale-invariant expression pattern from non-scaling morphogens contains rich information on the geometric structure of the decoder. We then apply and test our theory on the Drosophila gap gene system, providing a comprehensive understanding on this classic scaling problem.

Geometric structure of the decoder and the fate map

We first illustrate our basic idea using a bi-gradient model\textsuperscript{2,12,13}. In this simplified model, there are two morphogens, $M_1$ and $M_2$, having anterior and posterior exponential gradients with a fixed length constant $\lambda$ (Fig. 1a, length of a standard-sized embryo is defined as $L=1$). For larger (smaller) embryos, the effective length constant should shrink (expand) if measured in the relative coordinate ($y = y/L$, $M_1 = e^{-yL/\lambda}$, $M_2 = e^{-(1-y)L/\lambda}$, Fig. 1b). Consider for example the position $y=0.35$ as the boundary separating two different cell fates in the embryo. In a smaller (larger) embryo, as the absolute distance to both termini are shorter (longer) at this position, local levels of both morphogens are higher (lower). When $L$ varies, the $y=0.35$ point traces out a line on the $M_1$-$M_2$ plane (Fig. 1c). Therefore, in order to achieve perfect scaling, this $y$-constant line must be followed by the decision boundary of the decoder, which maps a ($M_1$, $M_2$) pair to a gene expression state (“fate”). In other words, the requirement imposed by scaling is enough to determine the effective input-output relation (coloring scheme) of the decoder on the $M_1$-$M_2$ plane, no matter how the decoder is implemented.
biochemically. The cell fate can also be represented by its equivalent position in wild-type (WT), denoted as $\tilde{y}$. In this case:

$$\tilde{y}(M_1, M_2) = \frac{\ln M_1}{\ln M_1 M_2}. \quad (1)$$

Once determined by its scale-invariant performance in WT embryos, the same decoder can be applied to mutant embryos where the maternal morphogen profiles are perturbed but the decoding machines are intact. In the case considered here, all $y$ points belonging to a WT embryo of size $L$ correspond to the hyperbolic curve $M_1 \cdot M_2 = e^{-L/\lambda}$ (Fig. 1c). On the other hand, consider a mutant embryo of which $L=1$ but the $M_1$ copy number is doubled:

$$M_1' = 2e^{-y_{mut}/\lambda}, \quad M_2' = e^{-(1-y_{mut})/\lambda}. \quad (2)$$

This mutant is also represented by a hyperbolic curve $M_1' \cdot M_2' = 2e^{-1/\lambda}$ (Fig. 1d). This curve is exactly the one corresponding to a WT embryo of size $L = 1 - \lambda \ln 2$, though points of the same cell fate locate at different $y$’s in WT and the mutant. For example, the blue-green boundary at $y=0.35$ in WT is shifted to 0.46 in the mutant. In general, for any $y_{mut}$ in this mutant embryo, there always exists a corresponding position $y_{WT}$ in WT embryo with the same morphogen values, hence the same cell fate $\tilde{y}$:

$$y_{WT}(y_{mut}) = \tilde{y}(y_{mut}) = y_{mut} - \frac{\lambda \ln 2}{1 - \lambda \ln 2}. \quad (3)$$

We call this mapping $\tilde{y}(y_{mut})$ the “fate-map” of this mutant, which can also be obtained by directly substituting Eq. 2 into Eq. 1. This fate map can be tested experimentally by plotting the positions $y_{WT}$ against $y_{mut}$ for the expression domain boundaries (Fig. 1e).
Fig. 1. Generating scaling output by reading the local values of two non-scaling gradients. (a) A schematic sketch with two embryos of different sizes. The two morphogen gradients are shown in the upper panel and the desired scaling output patterns are shown below. (b) The same relative position \( y \equiv x/L = 0.35 \) has higher level of both morphogens in a smaller embryo (marked by “o”) than a larger one (“x”). (c) In the \( M_1-M_2 \) space, an embryo of size \( L \) is represented by the curve \( M_1M_2 = e^{-L/\lambda} \). As \( L \) varies, the \( y = 0.35 \) point traces out a line. (d) Maternal morphogen profiles in a mutant are also represented by a curve in the \( M_1-M_2 \) space. The red curve stands for an \( L = 1 \) embryo where the \( M_1 \) dosage is doubled. The corresponding cell fates along this red curve, hence along the A-P axis of this mutant, can be directly read out. (e) The predicted “fate map” of the mutant in (c). All gene expression boundaries, if their positions in WT were plotted against their shifted positions in the mutant, should lie on the fate map.

Drosophila gap gene system

Following the arguments presented in the last section, we next construct a decoder for the Drosophila gap gene system, using the three major morphogen gradients Bcd, Nos/mHb and Tor. Based on experimental data\(^{33,35,38-43} \), the profiles of the morphogens are given by Eq. 4 below (see SI-1 and SI-4 for details) (Fig. 2a, Extended Data Fig. 1).

\[
\begin{align*}
Bcd(y) &= L^\beta e^{-yL/\lambda_B} \\
mHb(y) &= mHb_0 \left( 1 + e^{aL(y-1+(1-\lambda_H)/L)} \right)^{-1} \\
Tor(y) &= e^{-yL/\lambda_T} + e^{-(1-y)L/\lambda_B}
\end{align*}
\]

The gap genes (\( hb, Kr, kni \) and \( gt \)) are the first set of zygotic segmentation genes downstream of the maternal morphogens, and the first to display a scaling pattern\(^{29,34,35} \). The Drosophila embryo has around 100 rows of cells along the Anterior-Posterior (A-P) axis before gastrulation. Nearly any two of them can be distinguished by their gap gene expression\(^{44,45} \), so there are effectively around 100 different cell fates along the A-P axis and the fate map \( \tilde{y} \) should be discussed at the resolution of 0.01. To visualize these cell fates by colors, we group them into 8 classes according to the dominantly expressing gap gene (Fig. 2b). A standard-sized WT embryo is then represented by a 1-d curve in the space of (Bcd, mHb, Tor). When \( L \) varies, this curve sweeps out a 2-d WT manifold. Following our arguments in Fig. 1, the ideal output of a scaling decoder on this WT manifold can be immediately determined – lines of constant \( y \) values should have the same cell fate (Fig. 2c).
In reality, *Drosophila melanogaster* embryo length varies approximately between 450 and 570 μm (~±10%) across different fly stocks. To have a more realistic picture, we hereafter sample $L$ from a normal distribution $L \sim N(1, 0.1)$ to simulate the effects of length fluctuation across *Drosophila* stocks. Another important aspect is noise in morphogen profiles. When morphogen level approaches zero it should have huge relative noise thus cannot carry useful information. We introduced explicitly a Poisson noise term to the morphogen values to reflect this effect (Methods). As a result, the “colored lines” in Fig. 2c now transform into the WT-point-cloud in Fig. 2d.

Interestingly, for the *Drosophila* case the boundaries between regions of different colors are effectively linear – any decoder that achieves scaling should effectively behave like a set of linear classifiers. Therefore, we fit the phenomenological decision boundaries with planes (Methods). Points of different colors seem to be separated satisfactorily in this way (Fig. 2d, e, Extended Data Fig. 2d).

The three maternal gradients can not only determine boundaries of gap gene expression domains, but also ~100 distinct A-P cell fates as mentioned above. Thus, we can construct a (approximately) continuous version of the decoding function using more linear classifiers of this kind. Along the A-P axis, we fit 100 such classification planes at 100 equally spaced $y$ positions (Methods). The linear classifiers work sufficiently well with the decoding task. Fig. 2f shows the decoding result of the WT ensemble of Fig. 2d using the linear classifiers. Despite the presence of Poisson noise, positions ($\tilde{y}$) decoded by reading the maternal morphogen values are always close to the ground truth positions ($y$).
**Fig. 2.** The structure of a phenomenological decoder of *Drosophila*. (a) The three non-scaling maternal gradients in the coordinate normalized by embryo length $y = x/L$ (Eq. 4). The morphogen profiles for a standard size WT embryo ($L=1$, darker lines) and a smaller one ($L=0.8$, lighter lines) are shown. (b) About 100 different cell fates along the A-P axis are grouped into 8 domains according to the gap gene expression. The normalized gap gene profiles are adopted from Ref. 49 and a Gaussian smoothing is applied. (c) In the (Bcd, mHb, Tor) space, the standard-sized WT embryo is represented by the black curve along which $y$ varies from 0 to 1. When $L$ changes, each point on this curve traces out a line representing the morphogen values at this $y$ position in WT embryos of different sizes. Only the region corresponding to $L=0.8$~$1.2$ are plotted here. The $y$ lines shown there have spacing 0.01 along the A-P axis. (d) A Poisson noise is added to the morphogen levels and the embryo length is sampled from a normal distribution, turning the 2-d WT manifold in (c) to a point cloud. The decision boundaries can be well approximated by a set of linear planes. (e) A magnification of (d). The iv-v, v-vi and vi-vii boundary planes are shown. (f) Positions decoded from the morphogen values ($\bar{y}$) vs. the ground truth ($y$) for the WT point cloud in (d). Since gap gene expression is affected by the dorsoventral system when being very close to embryo termini, we only discuss $y$ between 0.05 and 0.95 hereafter. The root-mean-square-error is hardly larger than 1%. □

**The decoder quantitatively predicts phenotypes of morphogen mutants**

We next demonstrate that such a decoder based on scaling has a remarkable power to predict nearly all phenotypes of morphogen mutants in *Drosophila*. Note that the values of (Bcd, mHb, Tor) in mutants may lie outside of the WT region (color point cloud in Fig. 2d). In this case, we linearly extrapolate the classification planes (SI-2).

Fig. 3a-c show the intersections of the linearly extrapolated classification planes with the bottom/left/back faces of the cube in Fig. 2d (marked by $\alpha/\beta/\gamma$, on which Tor=0/Bcd=0/mHb=mHb0), with the same color scheme as in Fig. 2. Maternal morphogen null mutants lie on these faces. For example, in the nos' mutant mHb is equal to mHb0 throughout the entire embryo, corresponding to projecting the WT curve in the (Bcd, mHb, Tor) space onto the $\gamma$ plane. It is clear in Fig. 3c that along this projected nos' curve, domain iv is followed immediately by domain vii, indicating the loss of abdominal $kni$ (v) and $gt$ (vi) domains. This is exactly the case observed in experiments.45-47 As another example, consider the bcd tor. mHb is now the only morphogen gradient, decreasing from its maximum value to zero from the anterior to posterior pole. It is obvious in Fig. 3a-b that points on the mHb axis fall into the iv, v and vi domains successively, corresponding to three gap gene domains $Kr$, $kni$ and $gt$.
appearing successively in this mutant embryo. As the Bcd=Tor=mHb=0 point is
classified into domain vi, the *gt* domain should extend all the way to the posterior pole.
This is also the pattern observed experimentally\textsuperscript{45,48}.

More than the predictions on presence or absence of certain gap gene domains, a
continuous valued fate map $\tilde{y}(y_{\text{mut}})$ can be constructed by incorporating all the 100
classification planes. In Fig. 3d, the predicted fate map for WT and 11 maternal
morphogen mutants are shown as black curves. To test our predictions against
experiments, we identify the peak and boundary positions for all gap gene domains
(Table S1) from the published quantitative measurements of gap gene profiles in WT
and various mutants\textsuperscript{40,45,49-51}. For each of them, its position in mutant is plotted against
its WT positions (yellow squares in Fig. 3d). Remarkably, predictions and experiments
are consistent in all cases.

**Fig. 3.** Quantitative prediction on mutant fate map by the decoder. (a-c) The decoding
results on the bottom/left/back faces (marked by $\alpha/\beta/\gamma$) of the cube in Fig. 2d. Solid
black curves are projections of the \(L=1\) WT curve onto these planes, which also represents the standard-sized mutant embryos tor/bcd/nos, respectively. Arrowheads on them are pointing from head to tail. The predicted gap gene expression in these mutants can be read out along these lines. (d) Fate map \(\hat{y}(y)\) predicted for WT and another 11 different mutants (black lines) and the comparison with experimental measurements (yellow squares, cited from published works, see main text for references). See SI-6 for discussion on the panels of mhb and vas/exv/bcd6X. (e) The predicted domain boundaries in bcd as \(L\) changes. As \(L\) shrinks from 1.0 to 0.9 to 0.8 (solid, dashed and dotted lines), the \(Kr\) (iv) and \(kni\) (v) domains disappear successively. (f) Shift of cephalic furrow (CF) under Bcd dosage change. Solid line is our prediction and red dots with error bars are from experimental data\textsuperscript{40}. Dashed grey line shows the position of the same Bcd concentration as CF in WT.

Our model can also account for some recent and more quantitative experiments, in which multiple factors such as Bcd dosage, morphogen mutation and change of the embryo length were at play. For example, the model predicts that missing Bcd destroys scaling completely and the gap gene pattern changes greatly with \(L\). With decreasing embryo length, the bcd embryo losses domains iv (Kr) and then v (kni) (Fig. 3e). A recent experiment\textsuperscript{35} provides an excellent support for this prediction (Extended Data Fig. 5c). Another example is the shift of cephalic furrow (CF) (\(\hat{y} = 0.344\)) under mutation of the posterior or terminal morphogens plus Bcd dosage change\textsuperscript{40}. Our model quantitatively captured the shifts observed in experiment (Fig. 3f).

Decoder structure reveals underlying gene regulation

Predicted fate map can also be converted to a predicted gap gene pattern. For \(y_{\text{mut}}\) in a mutant embryo, the gap gene expression levels here can be approximated by the composite function \(G(\hat{y}(y_{\text{mut}}))\), where \(G\) stands for the WT gap gene pattern, and \(\hat{y}(y_{\text{mut}})\) is the fate map. Figs. 4a and c show two examples (solid lines). Measured profiles\textsuperscript{45} are shown as dotted lines in lighter colors for comparison.

Further analysis reveals the connection between the decoder structure and the underlying gene regulation. Consider the tor mutant as an example. As dictated by scaling, the decision boundaries Kr-kni, kni-gt and gt-hb should be inclined in 3-d, not perpendicular to the Bcd-mHb plane (Fig. 2e). This means that Tor should participate in positioning these boundaries to allow for scaling. Geometrically, when extrapolated to the Tor=0 plane following these inclined classification planes, a cell fate in WT should appear at a more posterior position than if being orthogonally projected.
downward. Thereby in the tor mutant, besides that posterior hb domain disappears, the rest of the abdominal domains should also shift posteriorly. This prediction is fully consistent with experiments (Fig. 4a). This example may help us to understand the ubiquitous “redundant” regulations in the gap gene network. According to the simplest interpretation, mHb gradient defines the anterior boundary of abdominal gt (vi) domain through inhibition; Gt inhibits kni, thereby setting the posterior boundary of kni (v) domain48. There is no “need”, in principle, for Tor to be involved. But the observed shift of kni boundary in tor clearly shows that in reality Tor contributes (probably through tll) to the repression on kni47,52, setting its posterior boundary together with mHb. We propose that such seemingly redundant regulations actually tune the slope of kni-gt classification plane, so that it could align with the angle required by scaling (Fig. 4b).

Another example deals with the bcd mutant (Fig. 4c). Bcd is well known to function in the anterior part. However, the region where Bcd plays a role seems to be much wider than naively expected – bcd mutant affects even domain vi and vii near the posterior pole. This aspect of Bcd should also contribute to tuning the decision boundary orientations to allow for scaling, as it has clearly been captured by our scaling-based phenomenological model. To be more precise, the decision plane representing the gt-hb (vi-vii) boundary at $\tilde{y}$=0.75 is:

$$-0.85\text{Bcd} - 0.12\text{mHb} + 0.45\text{Tor} = \text{Const.},$$

indicating that Tor should be effectively an activator for $hb$ here while Bcd should play a repressive role (Fig. 4d). This speculation is consistent with existing biological knowledges. Tor is long known to activate the posterior $hb$ domain through tailless(tll)52. And the effective repression by Bcd is most probably mediated by Kr and kni, upon whose mutation the posterior $hb$ domain expands anteriorly53. Similar line of arguments can be applied to other cases of regulations (SI-10).

**The decoder can be implemented with gene regulation**

Scaling requirement can implicate regulation. To see if the converse is true, i.e., if gene regulation can produce scale-invariant decision boundary, consider a toy model with a static anterior morphogen $B$ (like Bcd) of fixed length constant and a single gap gene $H$ whose initial condition $H_{init}$ serves as a posterior gradient (like mHb) (Fig. 4e).

The desired output is to have $H$ being activated in the anterior half with the boundary locating at $y$=0.5 regardless of the embryo length $L$. This requires that the morphogen levels marked by the black dots and empty triangles (Fig. 4e) should both lie on the $H$ boundary. This can be achieved with the regulation network shown in Fig. 4f (inset).
From a dynamical perspective, this network is well known to have bi-stability and Fig. 4f shows a typical bifurcation diagram. Within the bistable range, the $H$-high/$H$-low states are separated by a critical line (red squares), which means exactly the decision boundary between cell fates. If the activation strengths are properly tuned, this critical line can be adjusted to have identical slope as the desired decision boundary in Fig. 4g.

The gap gene network has more degrees of freedom and more scaling boundaries, and does not necessarily have to reach a dynamical attracting point. But the general idea is the same. Based on the known gap gene network shown in Fig. 4h, we construct a differential equation model (see SI-11 for details). If fitted to the WT data plus scaling requirement, the model can produce very similar decision boundaries as the phenomenological decoder (Fig. 4, i, j).

Fig. 4. Connecting the decoder with gene regulation. (a, c) The predicted gap gene pattern (solid lines) in $tor^-$ (a) and $bcd^-$ (c) are compared to measurements (dashed lines). The peak positions of the posterior $kni$, $hb$ and $gt$ domains are marked by filled arrowheads, and their WT positions by empty arrowheads. (b) Redundant regulation on the posterior boundary of $kni$ domain as required by scaling. (d) The vi-vii boundary ($\tilde{y}=0.75$) is set by the balance between the opposing gradients $Bcd$ and $Tor$. (e) The profiles of two morphogens in a toy model, shown for two embryos of standard size (darker lines) and larger size (lighter lines). (f) The bifurcation diagram for the network.
in the inset. A cell can reach one of the two bi-stable states depending on the values of the two morphogens, separated by the unstable manifold (red squares). This unstable manifold is the decision boundary separating the Hb-high and Hb-low fates. Its slope can be tuned by the activation strengths. (g) Within the realistic $L$ range (highlighted region), the $y=0.5$ line is well approximated by the decision boundary in (f) (red squares). (h) The known gap gene network\textsuperscript{17}. (i, j) The same plots as Fig. 3a and b, but using an ODE model of (h). □

**Concluding remarks**

We developed a theoretical framework on scale-invariant gene patterning from non-scaling signals and illustrated its application and utility in the *Drosophila* gap gene system, providing a unified understanding to scaling, regulation and the many observed phenomena in the *Drosophila* system. Since our framework is rather general and does not depend on specific molecular details, it can be readily extended to other systems (see an example in SI-13 on the long-germband insect *Megaselia abdita*).
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Methods

Fitting the linear classification planes.

The WT point cloud (Fig. 2d) used for fitting the linear classification planes are generated as follows. First, the A-P axis is discretized into 101 points y=0% to 100%. For each of the y position, we sample 400 embryo length values from the normal distribution \( L \sim N(1, 0.1) \) and calculate the corresponding (Bcd, mHb, Tor) levels using equation (4). The three morphogen values are noted by \( m = (m_1, m_2, m_3) \) for convenience. Obviously, \( 0 < m_1, m_2 < mHb_0 \) (\( mHb_0 = 0.1 \) here).

Then, a Poisson noise is added to each \( m_i \) by assuming the actual number of molecules is a Poisson variable \( n_i \) with \( \langle n_i \rangle = N^* m_i \), and the final morphogen value with noise is \( n_i / N \). The maximum molecule number \( N \) controls the noise magnitude, and set to \( N=1000 \) throughout the main text. Note that we do not claim that the actual morphogen noise follows independently identically Poisson distribution. And \( N \) does not correspond directly to the number of molecules per nucleus. Instead, \( N=1000 \) is chosen to make the positional error of Bcd gradient close to that measured by Gregor, et. al.\(^{39}\) (about 1~2% embryo length in the anterior half of embryo). Our model is not sensitive to the exact value of \( N \), see Extended Data Fig. 4, g-h for the results for \( N=500 \) or 2000.

The entire point cloud in Fig. 2d thus consists of 101 subsets \( m_i \), each of them have 400 points. The 100 classification planes are located at \( y=0.5\%\), 1.5\%, ..., 99.5\%, denoted as classifiers #1, ..., #100. Since gap gene expression is affected by the dorsoventral system when being very close to embryo termini, only classifiers #6 to #95 are considered in the main text. Each of the planes should perform the local classification task of distinguishing adjacent \( m \) point sets. For example, the plane locates at \( y=2.5\%\) should go through the noise-free \( y=2.5\%\) point for standard-sized embryo \( m_{L=1,y=2.5\%} \) by itself. And its orientation is such that it can best distinguishing the point sets \( U_L \cup U_{y=(0\%,1\%,2\%)} m_{L\times y} \) against \( U_L \cup U_{y=(3\%,4\%,5\%)} m_{L\times y} \). To find the best plane orientation numerically, we simply enumerate the Euler angles \( \theta \) and \( \phi \) of its normal vector at the resolution of 1° and find the one with the highest classification accuracy.

The noise due to finite sampling and discreetizing \( \theta \) and \( \phi \) can be eliminated by averaging the classification plane orientations for 25 repeats of the above sampling and fitting steps.

Predicting the fate-map function with the ensemble of linear classifiers.
In principle, 100 well-separated planes should divide the morphogen space (the cube with $0 < m_1 < 1$, $0 < m_2 < 0.1$, $0 < m_3 < 1$) into 101 slices, corresponding to $\tilde{y} = 0\%$ to 100%. If a query point falls into the slice $\tilde{y} = n\%$, it locates on the posterior side of classification planes #1 through #n, and on the anterior side of planes #n+1 to #100. Therefore, the corresponding cell fate $\tilde{y}$ can be read out from the classification results of all the linear classification planes (SI-2).

In some situations, however, the 100 linear classifiers could have contradictory outputs. Say, a point may be classified to the posterior side by classifier #70 but to the anterior side by #30. We introduce a “posterior dominance rule” to tackle this difficulty. Anytime when this happens, output of the anterior classifier (#30 here) is always ignored. The reason for us to introduce the posterior dominance rule is simple – some anterior classification planes may intersect with the much more posterior region of the point cloud, vary far from where they were fitted (Extended Data Fig. 3b). This posterior dominance rule works well, and finally yields all the results in Figs. 2-3.